

IN THE CLAIMS:

Please amend the claims below, as follows:

1 1. (Currently Amended) A method of substantially continuously optimising
2 a stochastic parameter θ that characterizes the instantaneously prevailing
3 readiness with which crop is processed in a harvesting machine, including the
4 step of recursively calculating the optimized parameter value in accordance
5 with the following algorithm:

6
$$\hat{\theta}(t) = f(\hat{\theta}(t-1), \varepsilon(t, \hat{\theta}(t-1))) \quad - (A)$$

7 wherein:

8 $\hat{\theta}(t)$ is the optimized stochastic parameter value at time t ; and
9 $\varepsilon(t, \hat{\theta}(t))$ is an error prediction function.

1 2. (Currently Amended) A method according to claim 1, characterised
2 whereinin that the algorithm (A) has the form:

3
$$\hat{\theta}(t) = f(\hat{\theta}(t-1), \dots, \hat{\theta}(t-n_g), \varepsilon(t), \dots, \varepsilon(t-n_e), t)$$

1 3. (Currently Amended) A method according to Claim 1-or-2, characterised
2 whereinin that the algorithm (A) has the form:

3
$$\hat{\theta}(t) = \hat{\theta}(t-1) + \gamma(t) r^{-1}(t) \psi(t, \hat{\theta}(t-1)) \varepsilon(t, \hat{\theta}(t-1))$$

4 wherein:

5 $\gamma(t)$ is a gain term;

6 $r(t)$ is a scalar approximation of a Hessian $V''(\vartheta)$ in which V is a
7 quadratic error criterion;

8 $\psi(t, \vartheta) = \frac{d\hat{y}(t, \vartheta)}{d\vartheta}$, in which $\hat{y}(t, \vartheta)$ is an estimation of a value indicative of
9 the effectiveness of crop processing in said harvesting machine, said estimation
10 being based on stochastic parameter ϑ ; and

11 $\varepsilon(t, \hat{\vartheta}(t-1))$ is the difference between the actual effectiveness value $y(t)$
12 and the estimated value $\hat{y}(t, \vartheta)$ based on the previously optimised parameter
13 $\hat{\vartheta}(t-1)$.

1 4. (Currently Amended) A method according to Claim 3, characterised
2 wherein that the algorithm (A) includes an estimation of $r(t)$ that is weighted to
3 reduce the influence, on the optimised parameter values $\hat{\vartheta}$, of past
4 measurements.

1 5. (Currently Amended) A method according to Claim 3-er-4, characterised
2 wherein that:
3 said stochastic parameter ϑ is usable in a model for the relation between
4 a value $u(t)$ indicative of the feedrate of crop into the harvesting machine and a
5 value $y(t)$ indicative of the effectiveness of an operation processing said crop in
6 said harvesting machine; and
7 said value $\hat{y}(t, \vartheta)$ is an estimation value of the effectiveness obtained by
8 the application of said model to the feedrate values $u(t)$.

1 6. (Currently Amended) A method according to Claim 5, ~~characterised~~
2 whereinin that said model comprises an exponential function.

1 7. (Currently Amended) A method according to Claim 6, ~~characterised~~
2 whereinin that said model has the form:

3 $\hat{y}(t, \vartheta) = \exp(\vartheta u(t)) - 1$ - (B)

1 8. (Currently Amended) A method according to ~~any of the Claims 5 to 7,~~
2 ~~characterised~~whereinin that:

3 said crop processing comprises separating useable crop parts from other
4 plant matter; and

5 said value $y(t)$ is indicative of a flow of useable crop losses in a selected
6 part (13/14) of the harvesting machine.

1 9. (Currently Amended) A method according to ~~any of the Claims 5 to 7,~~
2 ~~wherein~~characterised in that:

3 said crop processing operation comprises separating useable crop parts
4 from other plant matter; and

5 said value $y(t)$ is indicative of a flow of return crop in a selected part (15)
6 of the harvesting machine.

1 10. (Currently Amended) A method of operating a harvesting machine
2 comprising the steps of:

3 (i)-substantially continuously optimizing a stochastic parameter ϑ
4 that characterizes the instantaneously prevailing readiness with which
5 the harvesting machine processes crop; and
6 (ii)-substantially continuously adjusting a performance variable of the
7 harvesting machine in dependence on the instantaneous, optimized value $\hat{\vartheta}$ of
8 the said parameter in order to optimize the load of the harvesting machine so
9 as to keep a value $y(t)$ indicative of the effectiveness of said harvesting machine
10 below a predetermined value.

1 11. (Currently Amended) A method according to Claim 10, characterised
2 wherein that:
3 processing the crop comprises separating useable crop parts from other
4 plant matter;
5 optimizing the load of the harvesting machine comprises optimizing the
6 feedrate $u(t)$ of crop into the harvesting machine; and
7 the effectiveness value comprises losses $y(t)$ of useable crop parts.

1 12. (Currently Amended) A method according to Claim 10 or 11,
2 characterised wherein that the step (i) of continuously optimizing a stochastic
3 parameter ϑ includes carrying out the method steps of any of the Claims 1 to 9.
1 13. (Currently Amended) A method according to any of the Claims 10 to 12,
2 characterised wherein that the step (ii) of adjusting a performance variable of
3 the harvesting machine occurs in dependence on the output of an inverted form

4 of a yield loss estimation function:

5
$$\hat{y}(t, \vartheta) = \exp(\vartheta u(t)) - 1 \quad \text{-- (B)}$$

1 14. (Currently Amended) A method according to any of the Claims 10 to
2 13, characterised wherein in that adjusting a performance variable comprises
3 adjusting the travel speed of said harvesting machine or the actual cutting width
4 of a header of said harvesting machine.

1 15. (Currently Amended) A method of mapping one or more field lots for
2 variations in a stochastic parameter ϑ that characterizes the instantaneously
3 prevailing readiness with which crop is processed in a harvesting machine, the
4 method comprising the steps of:

5 (i) operating a harvesting machine to harvest crop in a said-field lot;

6 (ii) simultaneously measuring the machine load and the machine
7 effectiveness and determining the position of the machine in the field lot;

8 (iii) storing data indicative of the position of the harvesting machine at
9 time t ;

10 (iv) using the measured machine load data $u(t)$, and machine
11 effectiveness data $y(t)$ in an optimization of the-said parameter ϑ ; and

12 (v) mapping the optimized parameter values $\hat{\vartheta}$ obtained from the step
13 of using the measured machine load data $u(t)$ and machine effectiveness data
14 $y(t)$ in an optimization of said parameter ϑ ; (iv) so as to produce a parameter
15 map of the field lot.

1 16. (Currently Amended) A method according to Claim 15, ~~characterised~~
2 wherein in that the step of using the measured machine load data $u(t)$ and
3 machine effectiveness data $y(t)$ in an optimization of said parameter ϑ (iv)
4 includes carrying out an optimization according to ~~any of the Claims 1 to 9.~~

1 17. (Currently Amended) A method of operating a harvesting machine
2 comprising the steps of:
3 (i)—substantially continuously optimising a stochastic parameter ϑ that
4 characterises the instantaneously prevailing readiness with which the
5 harvesting machine separates useable crop parts from other plant matter; and
6 (ii)—sending a display signal, that is indicative of the instantaneously
7 parameter value $\hat{\vartheta}$, to a display device.

1 18. (Currently Amended) A method according to Claim 17, ~~characterised~~
2 wherein in that the step (i) of optimising a stochastic parameter ϑ includes
3 carrying out the method of ~~any of the Claims 1 to 9.~~

1 19. (Currently Amended) A method according to Claim 17 or 18,
2 ~~characterised wherein in that~~ the display signal indicates an abnormal parameter
3 value $\hat{\vartheta}$.

1 20. (Currently Amended) AmMethods according to Claim 1 ~~any of the~~
2 ~~preceding claims, characterised wherein in that~~ said harvesting machine is a
3 combine harvester and the crop is a grain-bearing plant.

1 21. (Currently Amended) A mMethods according to Claim 8-er 9 or to any
2 other Claim referring thereto, characterised whereinin that the said selected part
3 of the harvesting machine is selected from:
4 the straw walkers-(13);
5 the rotary separator;
6 the sieves-(14);
7 the grain elevator;
8 the return flow system-(15);
9 the cleaning section; or
10 the axial threshing and separating rotor;
11 of a combine harvester.